



Organization(s): Carnegie Mellon University; MIT; U. of Pennsylvania;
U.C. Berkeley; and Microcosm

MTO **Composite
CAD**

Title: Foundations for Microelectromechanical System Synthesis

Duration of Effort: October 1997 - October 1999

Principal Investigator(s): Gary K. Fedder
Phone: (412) 268-8443 / Email: fedder@ece.cmu.edu
Web: <http://www.ece.cmu.edu/~mems/memsyn>

Objective

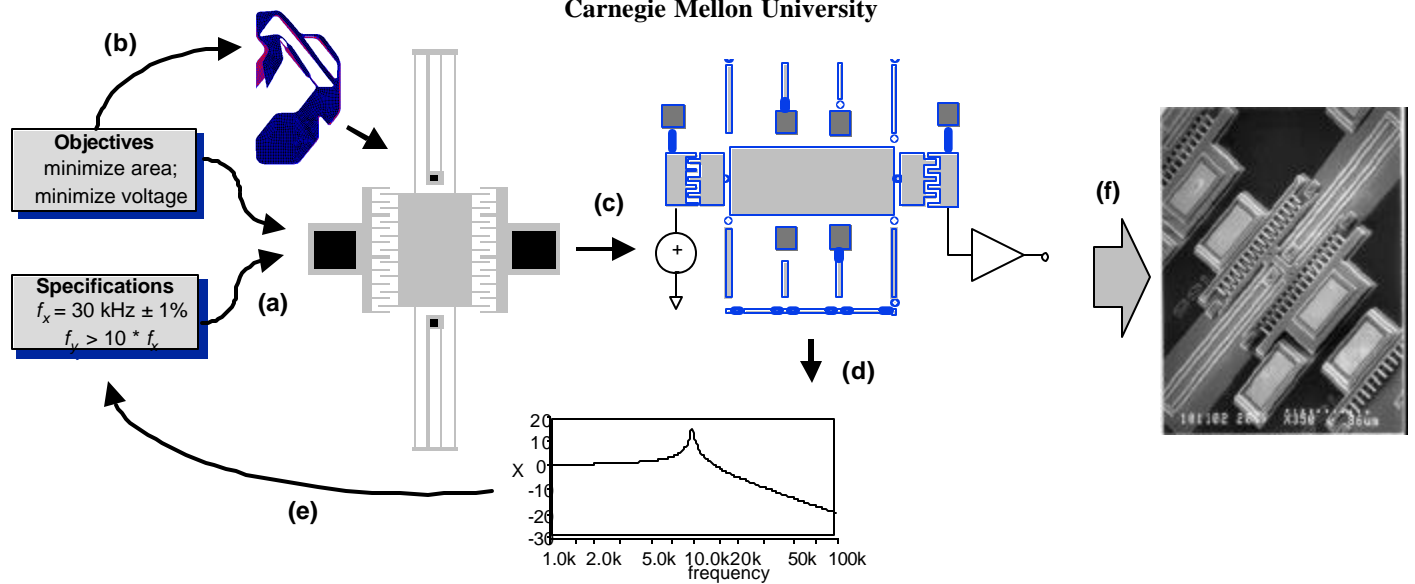
This project aims to shorten the design cycle for MEMS from years to days, and to enable design of more complex MEMS than can be handled today by developing a hierarchical design methodology and associated evaluation and synthesis tools.

Progress/Results

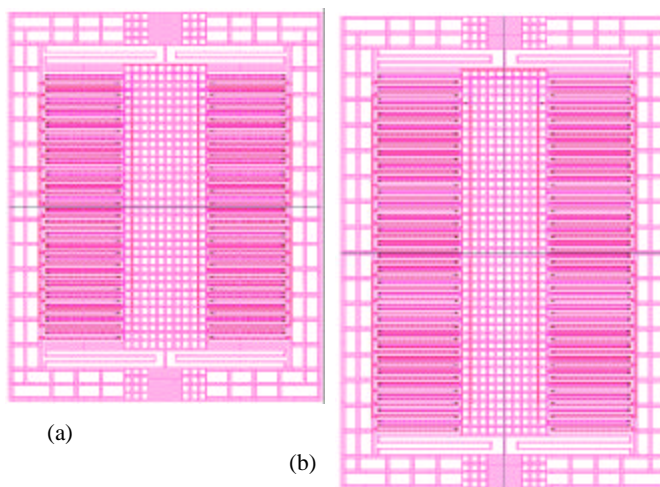
- Implemented a MEMS schematic representation in Saber and Spectre (NODAS) and in MATLAB (SUGAR) using in-plane models of beams, plates, gaps, combs, and anchors
- Released synthesis modules for comb-drive microresonators and for lateral microaccelerometers (polysilicon and CMOS-MEMS) with cross-axis sensitivity constraints
- Implemented an optimization-based shape synthesis module with force-deflection constraints which has created a 3x displacement amplifier for accelerometers
- Implemented a multilevel Newton nonlinear FE/BE electromechanics solver that allows efficient rigidification of user specified regions
- Completed a Java version for the Semiconductor Process Representation (SPR) populated with the MUMPs process and statistics
- Implemented MEMS shape grammar for structural (topology) synthesis of resonators

Status

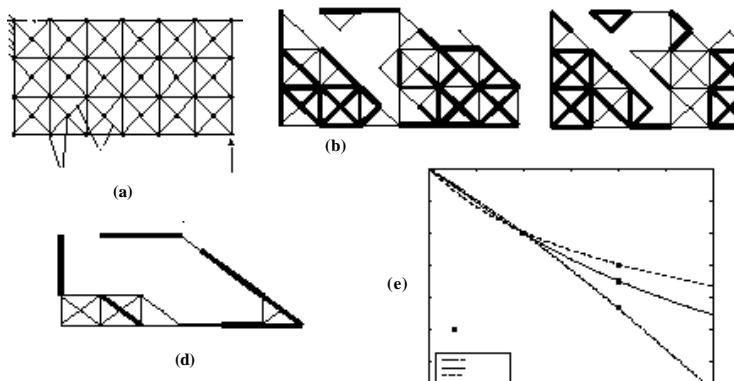
- Validating the MEMS schematic representation and component libraries
 - Verifying the CMOS-MEMS accelerometer synthesis module
 - Developing mode shape optimization formulations and nonlinear spring synthesis
 - Integrating search, control and evaluation aspects of structural (topology) synthesis into an agent-based system
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Semi-automated design flow for suspended MEMS. (a) Shape synthesis of components. (b) Layout synthesis from user



Synthesized CMOS-MEMS accelerometer layout (a) optimized for minimum area ($325 \times 425 \mu\text{m}^2$) (b) optimized for minimum noise ($325 \times 500 \mu\text{m}^2$)



Design Specifications for the Compliant Crimper Example Two-Point Synthesis of a Compliant Crimper (b) Optimal topology for design case I (c) Optimal topology for design case II (d) Optimal topology for design case III (e) Comparison of the force-deflection characteristics